

Asymptotic Bianchi IX model: diagonal and general cases

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Abstract

We make comparison of the dynamics of the diagonal and nondiagonal Bianchi IX models in the asymptotic regime near the cosmological singularity. Apart from the original variables, we use the Hubble normalized ones commonly applied in the examination of the dynamics of homogeneous models. Applying the dynamical systems method leads to the result that in both cases the continuous space of critical points is higher dimensional and they are of the nonhyperbolic type. This is a generic feature of the dynamics of both cases and seems to be independent on the choice of phase space variables. However, the topologies of the corresponding critical spaces are quite different. We conjecture that the nondiagonal case may carry a new type of chaos different from the one specific to the usually examined diagonal case.

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I. INTRODUCTION

According to the singularity theorems of General Relativity (GR), the evolution of an expanding universe is geodesically past-incomplete. The Belinskii, Khalatnikov and Lifshitz (BKL) [1, 2] scenario predicts that on approach to a space-like cosmological singularity the dynamics of gravitational field simplifies as time derivatives in Einstein equations dominate over spatial derivatives (see [3] for numerical support for BKL). In this regime the evolution of the Universe becomes strongly non-linear and chaotic, comprising expanding and contracting oscillatory phases around the singular point. One believes that an imposition of quantum rules onto this scenario may heal the singularity. Finding the nonsingular quantum BKL scenario would mean solving, to some extent, the generic cosmological singularity problem. Such a quantum theory could be used as a realistic model of the very early Universe.

Quantization of the BKL scenario should be preceded by the quantization of the Bianchi IX model. This seems to be a reasonable strategy because the BKL scenario has been obtained via analysis of the dynamics of the Bianchi IX model. The best prototype for the BKL scenario is the nondiagonal Bianchi IX model [2, 4, 5].

The quantization of the Bianchi IX model requires full understanding of its classical dynamics in terms of variables convenient for quantization procedure. Our recent paper [6] has initiated such analysis. As far as we know, the existing comprehensive analyses of the dynamics of the Bianchi IX model mainly concerns the diagonal case (see, [7, 8] and references therein). The examination of the dynamics presented in [9] of the nondiagonal case is mathematically satisfactory, but seems to be too complicated to be used in the canonical quantization scheme.

The three metric on space of the Bianchi IX model (in the synchronous reference system) can be chosen to be diagonal or nondiagonal one (during the entire evolution of the system) depending on the matter field. It turns out that the evolutions corresponding to both cases are essentially different near the cosmological singularity [4, 5]. The aim of this paper is examination of this difference in more details.

In this paper we use two quite different sets of variables parameterizing the dynamics: original BKL type [4, 5] and quasi Hubble normalized [10]. Making use the scale invariance of Einstein equations one can introduce variables which divided by the Hubble parameter become scale invariant [11]. The Hubble parameter, which in general spacetime is a geometrical average of expansion rates in three space directions, becomes infinite approaching the singularity. Although gravitational field variables like orthonormal frame variables also diverge approaching singularity, normalized by Hubble parameter remain finite and more useful for analytical analysis[8, 11] and they actually enabled successful numerical verification [3].

However, original BKL variables and Hubble normalized ones cannot be connected by canonical transformation. In both cases, applying dynamical systems method en-

ables identification of the spaces of non-isolated critical (equilibrium) points, which are of nonhyperbolic type. Topologies of these spaces are quite different, and making them explicit constitutes one of the main results of this paper. Additional result is expressing the asymptotic nondiagonal Bianchi IX model in terms of non-divergent variables similar to the Hubble normalized variables, thus enabling future more detailed investigations.

Our paper is organized as follows: Section II concerns the nondiagonal case. We introduce quasi Hubble normalized variables, examine the asymptotic dynamics in these (and BKL) variables, and identify the spaces of critical points of the corresponding vector fields. The diagonal case is considered in Sec. III, where we follow the steps of Sec. II. We conclude in Sec. IV. Appendix A concerns the issue of an effective form of the metric near the singularity. The choice of quotient coordinates, presented in App. B, enables making an extension of the interpretation of our results. We present the relationship between the BKL and our new variables in App. C. Finally, we apply the Poincaré sphere to deal with the space of critical points in finite region of phase space in App. D.

II. THE NONDIAGONAL CASE

The general form of a line element of the nondiagonal Bianchi IX model, in the synchronous reference system, reads

$$ds^2 = dt^2 - \gamma_{ab}(t)e_\alpha^a e_\beta^b dx^\alpha dx^\beta, \quad (1)$$

where Latin indices a, b, \dots run from 1 to 3 and label the frame vectors e_α^a , and Greek indices α, β, \dots take values 1, 2, 3 and concern space coordinates, and where γ_{ab} is a spatial metric.

It was shown in [1, 2] that near the cosmological singularity the general form of the metric γ_{ab} should be considered. Consequently, one cannot globally diagonalize the metric, i.e. for all values of time. After making use of the Bianchi identities, freedom in the rotation of the metric γ_{ab} and frame vectors e_α^a , one arrives at the well-defined, but complicated system of equations specifying the dynamics of the nondiagonal Bianchi IX model [5]. Finding that the anisotropy of space may grow without bound, when approaching the singularity, enables considerable simplification of the dynamics. Finally, the asymptotic form (near the cosmological singularity) of the dynamical equations of the nondiagonal Bianchi IX model reads [4–6]:

$$\frac{d^2 \ln a}{d\tau^2} = \frac{b}{a} - a^2, \quad \frac{d^2 \ln b}{d\tau^2} = a^2 - \frac{b}{a} + \frac{c}{b}, \quad \frac{d^2 \ln c}{d\tau^2} = a^2 - \frac{c}{b}, \quad (2)$$

where a, b, c are functions of time τ , satisfying the constraint

$$\frac{d \ln a}{d\tau} \frac{d \ln b}{d\tau} + \frac{d \ln a}{d\tau} \frac{d \ln c}{d\tau} + \frac{d \ln b}{d\tau} \frac{d \ln c}{d\tau} = a^2 + \frac{b}{a} + \frac{c}{b}, \quad (3)$$

and where τ is connected with the cosmological time variable t as follows

$$dt = \sqrt{\gamma} d\tau \quad (4)$$

(γ denotes the determinant of γ_{ab}).

Turning the above dynamics into Hamiltonian dynamics, one can examine qualitatively the mathematical structure of the corresponding physical phase space by using the dynamical systems method (DSM). It has been found that the *critical* points of the system have the following properties: (i) define a three-dimensional continuous subspace of \mathbb{R}^6 defined by the relation $a \gg b \gg c > 0$, with $a \rightarrow 0$ (see, Eq. (38) of [6] for more details), and (ii) are of the nonhyperbolic type.

The property (i) was already found long time ago [5] without using the DSM. The characteristic (ii) has been identified recently [6]. The latter property means that getting insight into the structure of the space of orbits near such critical set requires further examination of the exact nonlinear dynamics. The information obtained from linearization of the dynamics cannot be conclusive (see, e.g., [13]).

A. Quasi Hubble normalized variables

To make progress in understanding the structure of our critical set, we propose the parametrization of the dynamics by an analog of the so-called Hubble-normalized (HN) variables $(\tilde{\Sigma}_\alpha, \tilde{N}_\alpha)$ (see, e.g., [10]-[12] and references therein). They can be ascribed to the vacuum Bianchi type models in which case the spatial metric can be taken to be diagonal. Assuming a spacetime admitting a foliation $\mathcal{M} \mapsto \Sigma \times \mathbb{R}$, where Σ is spacelike, the line element of the spatially homogenous Bianchi type model reads, following the original notation of [10]-[12]:

$$ds^2 = -dt^2 + g_{11}(t) \omega^1 \otimes \omega^1 + g_{22}(t) \omega^2 \otimes \omega^2 + g_{33}(t) \omega^3 \otimes \omega^3, \quad (5)$$

where the ω^α 's are 1-forms on Σ invariant with respect to the action of a simply transitive group of motions on the leaf and subject to

$$d\omega^1 = -\hat{n}_1 \omega^2 \wedge \omega^3, d\omega^2 = -\hat{n}_2 \omega^3 \wedge \omega^1, d\omega^3 = -\hat{n}_3 \omega^1 \wedge \omega^2 \quad (6)$$

where \hat{n}_α are structure constants of the corresponding Lie algebra. In case of the Bianchi IX model $\hat{n}_\alpha = 1$.

Within this framework one can define the expansion θ and the shear σ^α_β :

$$\theta := -\text{tr}(k), \quad \sigma^\alpha_\beta := -k^\alpha_\beta + \frac{1}{3} \text{tr}(k) \delta^\alpha_\beta = \text{diag}(\sigma_1, \sigma_2, \sigma_3), \quad (7)$$

where $k_{\alpha\beta}$ is the second fundamental form associated with hypersurfaces $\{t = \text{const.}\}$ and σ_α fulfill $\Sigma_\alpha \sigma_\alpha = 0$. The Hubble variable H is proportional to the expansion $H = \theta/3$ and is related to changes of the spatial volume density via $d\sqrt{g}/dt = 3H\sqrt{g}$, where $g = \det g_{\alpha\beta}$. One can also define variables n_α

$$n_\alpha = \hat{n}_\beta \frac{g_\alpha^\beta}{\sqrt{g}}. \quad (8)$$

For the Bianchi IX model there exists a one-to-one correspondence between the set of the defined above variables $(H, \sigma_\alpha, n_\alpha)$ (with $\Sigma_\alpha \sigma_\alpha = 0$) and the standard ones $(g_{\alpha\beta}, k_{\alpha\beta})$. In this setting one can introduce the Hubble normalized (HN) variables $(\tilde{\Sigma}_\alpha, \tilde{N}_\alpha)$ (here we use symbol \sim for distinguishing the original variables and our subsequent ones), which are orthonormal frame variables σ_α and n_α normalized by the Hubble variable H :

$$\tilde{\Sigma}_\alpha := \frac{\sigma_\alpha}{H}, \quad \tilde{N}_\alpha := \frac{n_\alpha}{H}, \quad (9)$$

These are dimensionless quantities which fully describe the dynamics of the three-dimensional spacelike hypersurface Σ . Near the singularity, where space curvature and expansion all diverge, the HN variables remain finite, as dividing by divergent Hubble variable H factors out the overall expansion. Analysing dynamics of the Bianchi IX spacetimes near its singularity in terms of HN variables brought a lot of important and interesting results (see, e.g., [8, 10] and references therein).

Henceforth, it would be natural trying to formulate dynamics of the non-diagonal Bianchi IX model in terms of the HN variables. However there is the key difficulty laying in the definition of those variables, formulated for diagonal metrics, in case of the general Bianchi IX spacetime described by the metrics (1). This metrics is generally non-diagonal globally, although it can be diagonalized at each separate moment of time. According to [5] the exact 3-dimensional metric $\hat{\gamma}$ is given by

$$\hat{\gamma} = \hat{R}^{-1} \hat{\Gamma} \hat{R}, \quad (10)$$

where $\hat{\Gamma} = \text{diag}(\Gamma_1, \Gamma_2, \Gamma_3)$ and \hat{R} is an orthogonal matrix ($\hat{R}^T = \hat{R}^{-1}$, $\det \hat{R} = 1$). The matrix \hat{R} transforms the 3-dimensional metric tensor $g_{\alpha\beta}$ to the principal axes and this rotation might be described in terms of Euler angles (θ, φ, ψ) : rotation, precession and pure rotation. In other words $\hat{R} = \hat{R}_\theta \hat{R}_\varphi \hat{R}_\psi$, where \hat{R}_θ , \hat{R}_φ and \hat{R}_ψ are standard rotation matrices.

In the general case, the Euler angles (θ, φ, ψ) are time dependent and describe the rotation with respect to the frame vectors e^a , which are fixed. In the asymptotic regime the Euler angles become time independent, but Γ_α stay being functions of time.

One can diagonalize the metric $\hat{\gamma}$ in the asymptotic regime by using $\hat{R}\hat{\gamma}\hat{R}^{-1} = \hat{\Gamma}$. Since \hat{R} is time independent there, this diagonal form will exist until the gravitational system approaches the singularity. In this regime, the line element (1) can be presented as follows (see [1, 2] for more details)

$$ds^2 = dt^2 - (a^2 e_\alpha^{(1)} e_\beta^{(1)} + b^2 e_\alpha^{(2)} e_\beta^{(2)} + c^2 e_\alpha^{(3)} e_\beta^{(3)}) dx^\alpha dx^\beta, \quad (11)$$

where

$$a := \Gamma_1, \quad b := \Gamma_2 C^2 \cos^2 \theta_0, \quad c := \Gamma_3 C^4 \sin^2 \theta_0 \cos^2 \theta_0 \sin^2 \psi_0, \quad (12)$$

and where C is a constant of motion. The metric (11) describes only the oscillatory modes devoid of the rotation. Since a, b and c satisfy Eqs. (2) - (3), derived from the *exact* system of equations with nondiagonal form of 3-metric, they have encoded nondiagonal aspects of the metric, and the line element:

$$g_{11} := a^2, \quad g_{22} := b^2, \quad g_{33} := c^2, \quad g_{\alpha\beta} := 0 \quad \text{if } \alpha \neq \beta, \quad (13)$$

may be interpreted as presenting an *effective* 3-metric. This identification suggests that we have a sort of an effective diagonal metric $g_{\alpha\beta}$ near the cosmological singularity, i.e., in the asymptotic region of spacetime.

The effective 3-metric (13) is used below to introduce quasi-HN (qHN) variables. In this settings we define the new variables $(N_\alpha, \Sigma_\alpha)$ as follows:

$$N_1 := a^2 V, \quad N_2 := b^2 V, \quad N_3 := c^2 V, \quad (14)$$

$$\Sigma_1 := V \frac{d}{d\tau} \ln a - 1, \quad \Sigma_2 := V \frac{d}{d\tau} \ln b - 1, \quad \Sigma_3 := V \frac{d}{d\tau} \ln c - 1, \quad (15)$$

where $V = 3/\frac{d}{d\tau} \ln(abc)$, and where (a, b, c) satisfy Eqs. (2) and (3). Thus, $\Sigma_1 + \Sigma_2 + \Sigma_3 = 0$ identically, and $N_1 > 0, N_2 > 0, N_3 > 0$ as $abc \rightarrow 0$ near the singularity.

In what follows we will present similarities between the set of defined above variables and original HN ones.

The second fundamental form $k_{\alpha\beta}$ associated with (13) is defined to be

$$k_{\alpha\beta} := -\frac{1}{2} \frac{d}{dt} g_{\alpha\beta} = -\frac{1}{2} \frac{1}{abc} \frac{d}{d\tau} g_{\alpha\beta} =: -\frac{1}{2v} \dot{g}_{\alpha\beta}, \quad (16)$$

where due to (4) we have

$$dt/d\tau := \sqrt{g} = abc =: v, \quad (17)$$

and where $g := \det g_{\alpha\beta}$, so v is the spatial volume density.

If we take $k^\alpha_\beta := g^{\alpha\gamma} k_{\gamma\beta}$, the trace of the matrix $k_{\alpha\beta}$ reads

$$\text{tr}(k) = k^\alpha_\alpha = -\frac{1}{abc} \left(\frac{\dot{a}}{a} + \frac{\dot{b}}{b} + \frac{\dot{c}}{c} \right) = -\frac{1}{v} \frac{d}{d\tau} \ln v. \quad (18)$$

Defining the expansion θ by

$$\theta := \frac{d}{dt} \ln \sqrt{g} = \frac{1}{v} \frac{d}{d\tau} \ln v, \quad (19)$$

we get $\theta := -\text{tr}(k)$. The volume changes according to $dv/dt = \theta v$. Following the considerations in [10, 14], we define the Hubble variable

$$H := \frac{\theta}{3} = \frac{1}{3v} \frac{d}{d\tau} \ln v. \quad (20)$$

Thus the variables defined in Eqs. (14) and (15) coincide with Hubble normalized variables, namely:

$$\Sigma_\alpha := \frac{\sigma_\alpha}{H} = \frac{\sigma_{\bar{\alpha}}}{H} := \frac{(-k_{\bar{\alpha}} + \frac{1}{3} \text{tr}(k))}{H}, \quad (21)$$

where bared indices denote no summation convention, and $\Sigma_1 + \Sigma_2 + \Sigma_3 = 0$ identically. We also have

$$N_\alpha := \frac{n_\alpha}{H}, \quad \text{where} \quad n_\alpha := \frac{g_{\bar{\alpha}\bar{\alpha}}}{\sqrt{g}}, \quad (22)$$

directly corresponding to the definition (9) in our effective 3-metrics.

B. Dynamics

1. Finding the vector field

In what follows we derive the vector field corresponding to (2) - (3) entirely in terms of the qHN variables. Acting with $d/d\tau$ on (14) and making use of (2) leads to the following set of equations

$$\dot{N}_\alpha = N_\alpha (2\pi_\alpha - \frac{1}{3} N_1), \quad \alpha = 1, 2, 3. \quad (23)$$

One can rewrite (15) as follows

$$\Sigma_\alpha + 1 = 3\pi_\alpha/f, \quad \alpha = 1, 2, 3, \quad (24)$$

where $f := \pi_1 + \pi_2 + \pi_3$. Inserting (24) into (23) yields

$$\dot{N}_\alpha = \frac{N_\alpha}{3}(2(\Sigma_\alpha + 1)f - N_1). \quad (25)$$

Acting with $d/d\tau$ on both sides of (24) and using (2) gives

$$\dot{\Sigma}_1 = -\frac{N_1}{3}(4 + \Sigma_1) + \frac{3}{f}\sqrt{\frac{N_2}{N_1}}, \quad (26)$$

$$\dot{\Sigma}_2 = \frac{N_1}{3}(2 - \Sigma_2) + \frac{3}{f}\left(\sqrt{\frac{N_3}{N_2}} - \sqrt{\frac{N_2}{N_1}}\right), \quad (27)$$

$$\dot{\Sigma}_3 = \frac{N_1}{3}(2 - \Sigma_3) - \frac{3}{f}\sqrt{\frac{N_3}{N_2}}. \quad (28)$$

Due to (B14), and $\Sigma_1 + \Sigma_2 + \Sigma_3 = 0$, we have

$$f = 3\Pi. \quad (29)$$

Inserting (29) into (25) - (28), we finally obtain the following vector field specifying the dynamics entirely in the qHN variables:

$$\dot{N}_1 = 2\Pi N_1 (1 + \Sigma_1) - \frac{N_1^2}{3}, \quad (30)$$

$$\dot{N}_2 = 2\Pi N_2 (1 + \Sigma_2) - \frac{N_1 N_2}{3}, \quad (31)$$

$$\dot{N}_3 = 2\Pi N_3 (1 + \Sigma_3) - \frac{N_1 N_3}{3}, \quad (32)$$

$$\dot{\Sigma}_1 = \frac{N_1}{3}(-4 - \Sigma_1) + \frac{1}{\Pi}\sqrt{\frac{N_2}{N_1}}, \quad (33)$$

$$\dot{\Sigma}_2 = \frac{N_1}{3}(2 - \Sigma_2) + \frac{1}{\Pi}\left(\sqrt{\frac{N_3}{N_2}} - \sqrt{\frac{N_2}{N_1}}\right), \quad (34)$$

$$\dot{\Sigma}_3 = \frac{N_1}{3}(2 - \Sigma_3) - \frac{1}{\Pi}\sqrt{\frac{N_3}{N_2}}, \quad (35)$$

where $\Sigma_1 + \Sigma_2 + \Sigma_3 = 0$. The variable Π has to satisfy the constraint (B23), which corresponds to the original constraint (3). Taking into account the constraint yields the system of equations:

$$\dot{N}_1 = -\frac{N_1^2}{3} - \frac{N_1(1 + \Sigma_1) \left(N_1 + \sqrt{N_1^2 - 4\Sigma \left(\sqrt{\frac{N_2}{N_1}} + \sqrt{\frac{N_3}{N_2}} \right)} \right)}{\Sigma}, \quad (36)$$

$$\dot{N}_2 = -\frac{N_1 N_2}{3} - \frac{N_2(1 + \Sigma_2) \left(N_1 + \sqrt{N_1^2 - 4\Sigma \left(\sqrt{\frac{N_2}{N_1}} + \sqrt{\frac{N_3}{N_2}} \right)} \right)}{\Sigma}, \quad (37)$$

$$\dot{N}_3 = -\frac{N_1 N_3}{3} - \frac{N_3(1 - \Sigma_1 - \Sigma_2) \left(N_1 + \sqrt{N_1^2 - 4\Sigma \left(\sqrt{\frac{N_2}{N_1}} + \sqrt{\frac{N_3}{N_2}} \right)} \right)}{\Sigma}, \quad (38)$$

$$\dot{\Sigma}_1 = \frac{1}{3}(-4 - \Sigma_1)N_1 - \frac{2\Sigma\sqrt{\frac{N_2}{N_1}}}{N_1 + \sqrt{N_1^2 - 4\Sigma \left(\sqrt{\frac{N_2}{N_1}} + \sqrt{\frac{N_3}{N_2}} \right)}}, \quad (39)$$

$$\dot{\Sigma}_2 = \frac{1}{3}(2 - \Sigma_2)N_1 + \frac{2\Sigma \left(\sqrt{\frac{N_2}{N_1}} - \sqrt{\frac{N_3}{N_2}} \right)}{N_1 + \sqrt{N_1^2 - 4\Sigma \left(\sqrt{\frac{N_2}{N_1}} + \sqrt{\frac{N_3}{N_2}} \right)}}, \quad (40)$$

where $\Sigma := -3 + \Sigma_1^2 + \Sigma_1\Sigma_2 + \Sigma_2^2$.

2. Critical points of the dynamics

Direct inspection of the system (36) - (40) leads to the following identification of the set of the critical points:

$$S_{qHN} := \{(\Sigma_1, \Sigma_2, N_1, N_2, N_3) \mid (N_1 \rightarrow 0, N_2 \rightarrow 0, N_3 \rightarrow 0)\} \subset \bar{\mathbb{R}}^6, \quad (41)$$

in such a way that $N_3 \ll N_2 \ll N_1$ and $\sqrt{N_2/N_1} \ll N_1^2 \rightarrow 0$, and $\sqrt{N_3/N_2} \ll \sqrt{N_2/N_1} \rightarrow 0$, which imply that

$$\sqrt{N_3/N_2} \ll \sqrt{N_2/N_1} \ll N_1^2 \rightarrow 0. \quad (42)$$

One can avoid taking the uncommon form of the limits (42) by introducing new variables, which we consider in App. B. However, this does not change the character of critical points. They stay to be the nonhyperbolic ones.

3. The linearization of the vector field

One may verify, with some effort, that some elements of the Jacobian J of the system (36) - (40), evaluated at any point of S_{qHN} , are diverging. This behavior comes from differentiating square roots. However, when calculating characteristic polynomial of the Jacobian J at any point those divergencies cancel out giving

$$P(\lambda) = -\lambda^5, \quad (43)$$

so the eigenvalues are $(0, 0, 0, 0, 0)$.

Since the real parts of all eigenvalues of the Jacobian are equal to zero, we are dealing with the *nonhyperbolic* critical points.

Our system evolves asymptotically, as time goes to zero (when the system approaches the cosmological singularity), to the nonhyperbolic critical subspace with the coordinates $(\Sigma_1, \Sigma_2, N_1, N_2, N_3)$ given by

$$(\Sigma_1, \Sigma_2, 0, 0, 0). \quad (44)$$

Further analysis should be based on making use of the *exact* form of our vector field.

III. THE DIAGONAL CASE

In what follows we demonstrate that the asymptotic forms of the dynamics of the non-diagonal and diagonal Bianchi IX model are quite different.

The dynamics of the diagonal Bianchi IX in asymptotic regime near the singularity may be obtained from the asymptotic dynamics of non-diagonal model with zero rotation of principal values Γ_a of the three-dimensional metric tensor γ_{ab} around frame vectors e^a . It means that the Euler angles (θ, φ, ψ) , describing the rotation with respect to the frame vectors are fixed

$$(\theta, \varphi, \psi) = (\theta_0, \varphi_0, \psi_0), \quad (45)$$

so they are no longer the degrees of freedom of the system. In that case the Einstein equations for the general Bianchi IX model in the vicinity of singularity derived in [5] take the following form:

$$(\ln \Gamma_1)'' + \Gamma_1^2 - (\Gamma_2 - \Gamma_3)^2 = 0, \quad (46)$$

$$(\ln \Gamma_2)'' + \Gamma_2^2 - (\Gamma_1 - \Gamma_3)^2 = 0, \quad (47)$$

$$(\ln \Gamma_3)'' + \Gamma_3^2 - (\Gamma_1 - \Gamma_2)^2 = 0, \quad (48)$$

where we assumed that the total angular momentum of the system vanishes, unlike in the general case, with rotation frozen near the singularity but with non-zero total

angular momentum. The constraint equation, coming from the Bianchi identities, reads

$$\begin{aligned} & ((\ln \Gamma_1)')^2 + ((\ln \Gamma_2)')^2 + ((\ln \Gamma_3)')^2 - ((\ln \Gamma_1 \Gamma_2 \Gamma_3)')^2 \\ & + 2(\Gamma_1^2 + \Gamma_2^2 + \Gamma_3^2) - 4(\Gamma_1 \Gamma_2 + \Gamma_1 \Gamma_3 + \Gamma_2 \Gamma_3) = 0. \end{aligned} \quad (49)$$

For the comparison with (2) - (3), we rewrite (46) - (49) using the notation: $\tilde{a} := \Gamma_1$, $\tilde{b} := \Gamma_2$, $\tilde{c} := \Gamma_3$, and get

$$(\ln \tilde{a})'' = (\tilde{b} - \tilde{c})^2 - \tilde{a}^2, \quad (50)$$

$$(\ln \tilde{b})'' = (\tilde{c} - \tilde{a})^2 - \tilde{b}^2, \quad (51)$$

$$(\ln \tilde{c})'' = (\tilde{a} - \tilde{b})^2 - \tilde{c}^2, \quad (52)$$

with the dynamical constraint:

$$((\ln \tilde{a})')^2 + ((\ln \tilde{b})')^2 + ((\ln \tilde{c})')^2 - ((\ln \tilde{a} \tilde{b} \tilde{c})')^2 + 2(\tilde{a}^2 + \tilde{b}^2 + \tilde{c}^2) - 4(\tilde{a} \tilde{b} + \tilde{a} \tilde{c} + \tilde{b} \tilde{c}) = 0. \quad (53)$$

It is easy to see that the dynamics of the diagonal and nondiagonal cases are quite different. Let us indicate just one aspect of this non-equivalence. Namely, it is clear that Eqs. (50) - (53) are symmetric with respect to the permutations:

$$(\tilde{a}, \tilde{b}, \tilde{c}) \rightarrow (\tilde{b}, \tilde{c}, \tilde{a}) \rightarrow (\tilde{c}, \tilde{a}, \tilde{b}), \quad (54)$$

whereas Eqs. (2) - (3) do not have the corresponding symmetry

$$(a, b, c) \rightarrow (b, c, a) \rightarrow (c, a, b). \quad (55)$$

The difference results from the fact that Eqs. (2) - (3) has been obtained by imposition onto the original set of equations defining the nondiagonal dynamics (see, Eqs. (2.14)-(2.20) in [5]) the condition

$$\Gamma_1 \gg \Gamma_2 \gg \Gamma_3 \quad (56)$$

which implies Eq. (45), but not vice versa.

A. Dynamical system analysis

Introducing the notation:

$$x_1 := \ln \tilde{a}, \quad x_2 := \ln \tilde{b}, \quad x_3 := \ln \tilde{c}, \quad p_1 := \dot{x}_1, \quad p_2 := \dot{x}_2, \quad p_3 := \dot{x}_3, \quad (57)$$

we rewrite the system (50) - (52) as follows

$$\dot{x}_1 = p_1, \quad (58)$$

$$\dot{x}_2 = p_2, \quad (59)$$

$$\dot{x}_3 = p_3, \quad (60)$$

$$\dot{p}_1 = (e^{x_2} - e^{x_3})^2 - e^{2x_1}, \quad (61)$$

$$\dot{p}_2 = (e^{x_3} - e^{x_1})^2 - e^{2x_2}, \quad (62)$$

$$\dot{p}_3 = (e^{x_1} - e^{x_2})^2 - e^{2x_3}, \quad (63)$$

with the constraint corresponding to (53) in the form

$$p_1 p_2 + p_1 p_3 + p_2 p_3 - (e^{2x_1} + e^{2x_2} + e^{2x_3}) + 2(e^{x_1+x_2} + e^{x_1+x_3} + e^{x_2+x_3}) = 0. \quad (64)$$

It is easy to see that the critical points of the vector field (58) - (63), satisfying (64), are defined by

$$\tilde{S}_{B0} := \{(x_1, x_2, x_3, p_1, p_2, p_3) \in \bar{\mathbb{R}}^6 \mid (x_1, x_2, x_3 \rightarrow -\infty) \wedge (p_1 = 0 = p_2 = p_3)\}, \quad (65)$$

$$\tilde{S}_{B1} := \{(x_1, x_2, x_3, p_1, p_2, p_3) \in \bar{\mathbb{R}}^6 \mid (x_1 \rightarrow -\infty, x_2 = x_3) \wedge (p_1 = 0 = p_2 = p_3)\}, \quad (66)$$

$$\tilde{S}_{B2} := \{(x_1, x_2, x_3, p_1, p_2, p_3) \in \bar{\mathbb{R}}^6 \mid (x_2 \rightarrow -\infty, x_3 = x_1) \wedge (p_1 = 0 = p_2 = p_3)\}, \quad (67)$$

$$\tilde{S}_{B3} := \{(x_1, x_2, x_3, p_1, p_2, p_3) \in \bar{\mathbb{R}}^6 \mid (x_3 \rightarrow -\infty, x_1 = x_2) \wedge (p_1 = 0 = p_2 = p_3)\}. \quad (68)$$

There are no *strong* relations among x_1 , x_2 and x_3 in each of the above sets, contrary to the nondiagonal case (see the statement following Eq. (B9)).

One can solve the constraint equation (64) setting, e.g.

$$p_3 = \frac{e^{2x_1} + e^{2x_2} + e^{2x_3} - 2e^{x_1+x_2} - 2e^{x_1+x_3} - 2e^{x_2+x_3} - p_1 p_2}{p_1 + p_2}, \quad (69)$$

which turns the vector field (58) - (63) into

$$\dot{x}_1 = p_1, \quad (70)$$

$$\dot{x}_2 = p_2, \quad (71)$$

$$\dot{x}_3 = \frac{e^{2x_1} + e^{2x_2} + e^{2x_3} - 2e^{x_1+x_2} - 2e^{x_1+x_3} - 2e^{x_2+x_3} - p_1 p_2}{p_1 + p_2}, \quad (72)$$

$$\dot{p}_1 = (e^{x_2} - e^{x_3})^2 - e^{2x_1}, \quad (73)$$

$$\dot{p}_2 = (e^{x_3} - e^{x_1})^2 - e^{2x_2}. \quad (74)$$

The above system has the same critical subspaces as the one without the constraint built into it. The Jacobian associated with the system (70) - (74) is found to be

$$\begin{pmatrix} 0 & 0 & -\frac{2e^{x_1}(-e^{x_1}+e^{x_2}+e^{x_3})}{p_1+p_2} & -2e^{2x_1} & 2e^{x_1}(e^{x_1}-e^{x_3}) \\ 0 & 0 & -\frac{2e^{x_2}(e^{x_1}-e^{x_2}+e^{x_3})}{p_1+p_2} & 2e^{x_2}(e^{x_2}-e^{x_3}) & -2e^{2x_2} \\ 0 & 0 & -\frac{2e^{x_3}(e^{x_1}+e^{x_2}-e^{x_3})}{p_1+p_2} & 2e^{x_3}(-e^{x_2}+e^{x_3}) & 2e^{x_3}(-e^{x_1}+e^{x_3}) \\ 1 & 0 & -\frac{(e^{x_1}-e^{x_2})^2+e^{2x_3}-2e^{x_3}(e^{x_1}+e^{x_2})+p_2^2}{(p_1+p_2)^2} & 0 & 0 \\ 0 & 1 & -\frac{(e^{x_1}-e^{x_2})^2+e^{2x_3}-2e^{x_3}(e^{x_1}+e^{x_2})+p_1^2}{(p_1+p_2)^2} & 0 & 0 \end{pmatrix}^T$$

The characteristic polynomial evaluated at the critical subspaces reads:

$$P(\lambda) = -\lambda^5. \quad (75)$$

Hence, we can conclude that the character of the critical hypersurfaces (65) - (68) is the *nonhyperbolic* one.

B. Introducing the qHN variables

For the diagonal case we define the qHN variables $(M_\alpha, \Omega_\alpha)$ as follows:

$$M_1 := \tilde{a}^2 \tilde{V}, \quad M_2 := \tilde{b}^2 \tilde{V}, \quad M_3 := \tilde{c}^2 \tilde{V}, \quad (76)$$

$$\Omega_1 := \tilde{V} \frac{d}{d\tau} \ln \tilde{a} - 1, \quad \Omega_2 := \tilde{V} \frac{d}{d\tau} \ln \tilde{b} - 1, \quad \Omega_3 := \tilde{V} \frac{d}{d\tau} \ln \tilde{c} - 1, \quad (77)$$

where $\tilde{V} := 3/\frac{d}{d\tau} \ln(\tilde{a}\tilde{b}\tilde{c})$, and $M_\alpha > 0, \forall \alpha$, as near the singularity $\tilde{a}\tilde{b}\tilde{c} \rightarrow 0$.

Making use of (61) - (63) we can rewrite the constraint (64) in the form:

$$p_1 p_2 + p_1 p_3 + p_2 p_3 - (\dot{p}_1 + \dot{p}_2 + \dot{p}_3) = 0. \quad (78)$$

Using (77) and applying the analysis similar as in the nondiagonal case (B10) - (B14) we get:

$$p_1 = \Omega(1 + \Omega_1), \quad p_2 = \Omega(1 + \Omega_2), \quad p_3 = \Omega(1 + \Omega_3), \quad (79)$$

where $\Omega \in C^1(\mathbb{R})$, and where $\Omega_1 + \Omega_2 + \Omega_3 = 0$ due to (77).

Now, using (76) and (61) - (63) we arrive to the expressions:

$$\dot{p}_1 = \Omega(-M_1 + M_2 + M_3 - 2\sqrt{M_2 M_3}), \quad (80)$$

$$\dot{p}_2 = \Omega(M_1 - M_2 + M_3 - 2\sqrt{M_1 M_3}), \quad (81)$$

$$\dot{p}_3 = \Omega(M_1 + M_2 - M_3 - 2\sqrt{M_1 M_2}). \quad (82)$$

Inserting (79) - (82) into (78) leads to the following expression for the constraint in terms of the qHN variables:

$$\Omega (\Omega \Omega_{123} - M_{123}) = 0, \quad (83)$$

where $\Omega_{123} := 3 + \Omega_1\Omega_2 + \Omega_1\Omega_3 + \Omega_2\Omega_3$ and $M_{123} := M_1 + M_2 + M_3 - 2(\sqrt{M_1M_2} + \sqrt{M_1M_3} + \sqrt{M_2M_3})$. Eq. (83) has two solutions: $\Omega = 0$, and $\Omega = M_{123}/\Omega_{123}$.

C. The vector field

Acting with $d/d\tau$ on (76) and (77), and using the expressions (79) - (82) leads, after some simple but lengthy rearrangements, to the following vector field:

$$\dot{M}_1 = \frac{1}{3}M_1M_{123}(6\Omega_0(1 + \Omega_1) - 1), \quad (84)$$

$$\dot{M}_2 = \frac{1}{3}M_2M_{123}(6\Omega_0(1 + \Omega_2) - 1), \quad (85)$$

$$\dot{M}_3 = \frac{1}{3}M_3M_{123}(6\Omega_0(1 + \Omega_3) - 1), \quad (86)$$

$$\dot{\Omega}_1 = -M_1 + M_2 + M_3 - 2\sqrt{M_2M_3} - \frac{1}{3}M_{123} (\Omega_1 + 1), \quad (87)$$

$$\dot{\Omega}_2 = M_1 - M_2 + M_3 - 2\sqrt{M_1M_3} - \frac{1}{3}M_{123} (\Omega_2 + 1), \quad (88)$$

$$\dot{\Omega}_3 = M_1 + M_2 - M_3 - 2\sqrt{M_1M_2} - \frac{1}{3}M_{123} (\Omega_3 + 1), \quad (89)$$

where $\Omega_0 = 0$ or $\Omega_0 = 1/\Omega_{123}$, and the identity $\Omega_1 + \Omega_2 + \Omega_3 = 0$ must be satisfied. Equations (87)-(89) fulfill this identically which shows self-consistence of the set (84)-(89).

D. Critical points

The critical points of the system (84) - (89), satisfying (83), define the set of critical hypersurfaces:

$$S_0 := \{(\Omega_1, \Omega_2, \Omega_3, M_1, M_2, M_3) \mid M_1 = 0 = M_2 = M_3\} \subset \bar{\mathbb{R}}^6, \quad (90)$$

$$S_1 := \{(\Omega_1, \Omega_2, \Omega_3, M_1, M_2, M_3) \mid M_1 = 0, M_2 = M_3\} \subset \bar{\mathbb{R}}^6, \quad (91)$$

$$S_2 := \{(\Omega_1, \Omega_2, \Omega_3, M_1, M_2, M_3) \mid M_2 = 0, M_3 = M_1\} \subset \bar{\mathbb{R}}^6, \quad (92)$$

$$S_3 := \{(\Omega_1, \Omega_2, \Omega_3, M_1, M_2, M_3) \mid M_3 = 0, M_1 = M_2\} \subset \bar{\mathbb{R}}^6. \quad (93)$$

The Jacobian associated with the vector field (84) - (89), satisfying (83), evaluated at any point of $\{S_0, S_1, S_2, S_3\}$ has diverging components arising from differentiating terms of the type $\sqrt{M_1 M_2}$ and in the limit $M_1 \mapsto 0$ (or other M 's going to zero). However, calculating characteristic polynomial and taking the value of its coefficient at the critical subspaces leads to the following result:

$$P(\lambda) = \lambda^6, \quad (94)$$

Hence, we can conclude that the character of the critical hypersurfaces (90) - (93) is the *nonhyperbolic* one.

IV. CONCLUSIONS

Near the cosmological singularity, an evolution of the Bianchi IX model is an infinite sequence of the so called eras each of which consists of the Kasner type epochs [1]. In the *diagonal* case, each epoch can be described, e.g., by the relation $\tilde{\Gamma}_1 \sim \tilde{\Gamma}_2 > \tilde{\Gamma}_3$ (where \sim means coupled) called an oscillation¹. The dynamics of the *nondiagonal* model has essentially different structure [4, 5]: the oscillation of the diagonal type, e.g., $\Gamma_1 \sim \Gamma_2 > \Gamma_3$ enters sooner or later the relation $\Gamma_1 > \Gamma_2 > \Gamma_3$, which turns into the strong relation $\Gamma_1 \gg \Gamma_2 \gg \Gamma_3$. Finally, the system approaches the singularity in a finite proper time.

The difference between the dynamics of the diagonal and nondiagonal cases leads to different topological structures of the corresponding sets of critical points. In the former case, this set consists of three hypersurfaces in $\bar{\mathbb{R}}^6$ having the same topology, Eqs. (91)-(93), and one set, Eq. (90), with the simple topology of $\bar{\mathbb{R}}^3$. In the latter case, the set of critical points has sophisticated topology, defined by Eq. (41), quite different from the diagonal case. Similar relationship occurs between the critical sets expressed in term of the BKL variables. However, in both cases the critical sets consist of the *nonhyperbolic* type of critical points.

The nonhyperbolicity is expected to be directly linked with the chaoticity of the dynamics of the Bianchi IX model. Near the singularity, the scenario of the dynamics of the diagonal case (see, e.g. [15, 16]), sooner or later, turns into that of the nondiagonal one [17]. We conjecture that due to different topologies of the critical spaces the chaoticity aspects of both cases may be quite different. One may also expect that general solution to the dynamics of the diagonal case cannot be generalized to a generic solution of general relativity (that we call the BKL scenario) implied by general solution to the nondiagonal case [18]. Further studies are required to get insight into this intriguing issue.

¹ There can also occur small oscillations $\tilde{\Gamma}_1 \sim \tilde{\Gamma}_2 \gg \tilde{\Gamma}_3$, but they last for a finite interval of time and can be ignored.

Our main concern is the nonhyperbolicity of equilibrium points in both diagonal and general cases. They do not define a set of *isolated* points, but a three-dimensional *continuous* space. Thus, our choice of phase space variables seems to be unsatisfactory. We have already tried [6] to use the so-called blowing up technic initiated by McGehee [19] to avoid this obstacle, but with no success. More sophisticated approach based on σ -process of algebraic geometry proposed in [7] may bring some progress, but it leads to a noncanonical variables that we try to avoid. Another framework proposed for the spacially inhomogeneous models [11], within Hubble-normalized approach, can be probably specialized to the homogeneous models. However, this formulation is again a noncanonical one which we do not favour.

The way out seems to be giving up the insistence on dealing entirely with canonical formulations and planning making use of coherent states quantization methods (based on phase space structure of the underlying system) that we have recently applied to the diagonal Bianchi IX model [20]. In such a case making use of the results of [11] to elucidate mathematical structure of the physical phase space specific to the dynamics of the Bianchi IX model (in both considered cases) would make sense. This is supposed to be the next step of our investigation and the results of the present paper could be used as a starting point. Another approach would be based on modification of the definition of the Hubble-normalized variables that we use in the present paper.

The fact that some critical points occur at infinity is not an obstacle. The mapping of the set of critical points onto the Poincaré sphere (considered, e.g., for the nondiagonal case, in App. C) does not change the type of the criticality. It stays to be of nonhyperbolic type. Thus, compactification of phase space does not help.

It seems that the nonhyperbolicity of the equilibrium points distributed in a continuous way in higher dimensional space is a generic feature of the dynamics of the Bianchi IX model and cannot be avoided. These properties may correspond to mathematical structure [12, 21] underlying stochasticity of considered dynamics [22, 23], and needs to be further examined.

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Appendix A: Quotient coordinates

In order to avoid defining critical surface in term of the limits $\sqrt{N_3/N_2} \ll \sqrt{N_2/N_1} \ll N_1^2 \rightarrow 0$, one can introduce quotient coordinates:

$$u := \frac{1}{N_1^2} \sqrt{\frac{N_2}{N_1}}, \quad (\text{A1})$$

$$v := \frac{1}{N_1^2} \sqrt{\frac{N_3}{N_2}}. \quad (\text{A2})$$

Then the system of equations (36) - (40) takes the following form:

$$\dot{N}_1 = -\frac{N_1^2}{3} - \frac{N_1^2(1 + \Sigma_1) \left(1 + \sqrt{1 - 4(u+v)\Sigma}\right)}{\Sigma}, \quad (\text{A3})$$

$$\dot{u} = uN_1 \frac{\Sigma_0 + 3(4 + 5\Sigma_1 - \Sigma_2)\sqrt{1 - 4(u+v)\Sigma}}{6\Sigma}, \quad (\text{A4})$$

$$\dot{v} = vN_1 \frac{\Sigma_0 + 3(4 + 5\Sigma_1 + 2\Sigma_2)\sqrt{1 - 4(u+v)\Sigma}}{6\Sigma}, \quad (\text{A5})$$

$$\dot{\Sigma}_1 = -\frac{1}{3}(4 + \Sigma_1)N_1 - \frac{2uN_1\Sigma}{1 + \sqrt{1 - 4(u+v)\Sigma}}, \quad (\text{A6})$$

$$\dot{\Sigma}_2 = -\frac{1}{3}(-2 + \Sigma_2)N_1 + \frac{2(u-v)N_1\Sigma}{1 + \sqrt{1 - 4(u+v)\Sigma}} \quad (\text{A7})$$

where $\Sigma_0 = 15\Sigma_1 + 4\Sigma_1^2 - 3\Sigma_2 + 4\Sigma_1\Sigma_2 + 4\Sigma_2^2$ and $\Sigma = -3 + \Sigma_1^2 + \Sigma_1\Sigma_2 + \Sigma_2^2$. The left hand sides of equations (A3)-(A4) vanish for $N_1 = 0 = u = v$.

The set of critical points of the vector field (A3)-(A7) is easily found to be

$$\tilde{S}_{qHN} := \{(\Sigma_1, \Sigma_2, N_1, u, v) \mid N_1 = 0 = u = v\} \subset \bar{\mathbb{R}}^5. \quad (\text{A8})$$

The characteristic polynomial is $P(\lambda) = -\lambda^5$. Thus, the character of corresponding critical surface is nonhyperbolic.

One may speculate that \tilde{S}_{qHN} corresponds to S_0 of Eq. (90) so the underlying dynamics of corresponding vector fields have some common feature. One may further speculate that both S_0 of Eq. (90) and (A8) correspond to some new form of chaoticity, whereas (91)-(93) are specific to the well known attractor of the diagonal case.

Appendix B: Relationship between old and new variables

Let us rewrite Eqs. (2) as follows

$$\dot{q}_1 = \pi_1, \quad (\text{B1})$$

$$\dot{q}_2 = \pi_2, \quad (\text{B2})$$

$$\dot{q}_3 = \pi_3, \quad (\text{B3})$$

$$\dot{\pi}_1 = -\exp(2q_1) + \exp(q_2 - q_1), \quad (\text{B4})$$

$$\dot{\pi}_2 = \exp(2q_1) - \exp(q_2 - q_1) + \exp(q_3 - q_2), \quad (\text{B5})$$

$$\dot{\pi}_3 = \exp(2q_1) - \exp(q_3 - q_2), \quad (\text{B6})$$

where $q_1 := \ln a$, $q_2 := \ln b$, $q_3 := \ln c$, $\pi_1 := \dot{q}_1$, $\pi_2 := \dot{q}_2$, $\pi_3 := \dot{q}_3$ are new variables. Thus, the constraint (3) reads

$$\pi_1\pi_2 + \pi_1\pi_3 + \pi_2\pi_3 = \exp(2q_1) + \exp(q_2 - q_1) + \exp(q_3 - q_2). \quad (\text{B7})$$

Making use of (B1)-(B6) one can present (B7) in the form

$$\pi_1\pi_2 + \pi_1\pi_3 + \pi_2\pi_3 = 4\dot{\pi}_1 + 3\dot{\pi}_2 + 2\dot{\pi}_3. \quad (\text{B8})$$

One can easily verify that the critical points of the dynamical system (B1)-(B7) are of the *nonhyperbolic* type and coincide with the set of critical points S_B determined in [6]. Thus, the set of critical points S_B (in terms of q_α and π_α variables) is given by

$$S_B := \{(q_1, q_2, q_3, \pi_1, \pi_2, \pi_3) \in \bar{\mathbb{R}}^6 \mid (q_1 \rightarrow -\infty, q_2 - q_1 \rightarrow -\infty, q_3 - q_2 \rightarrow -\infty) \wedge (\pi_1 = 0 = \pi_2 = \pi_3)\}, \quad (\text{B9})$$

where $\bar{\mathbb{R}} := \mathbb{R} \cup \{-\infty, +\infty\}$. The infinities in (B9) should be approached in such a way that $q_1 \gg q_2 \gg q_3$, which corresponds to $a \gg b \gg c$ found in [5].

Now, we rewrite the vector field (B1)-(B7) in terms of the qHN variables N_α and Σ_α . Using (15) we get

$$\Sigma_\alpha = 3\pi_\alpha / (\pi_1 + \pi_2 + \pi_3) - 1. \quad (\text{B10})$$

Eq. (B10) can be presented in a matrix form as follows

$$\begin{bmatrix} \Sigma_1 - 2 & 1 + \Sigma_1 & 1 + \Sigma_1 \\ 1 + \Sigma_2 & \Sigma_2 - 2 & 1 + \Sigma_2 \\ 1 + \Sigma_3 & 1 + \Sigma_3 & \Sigma_3 - 2 \end{bmatrix} \begin{bmatrix} \pi_1 \\ \pi_2 \\ \pi_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}. \quad (\text{B11})$$

One may verify that the determinant of the 3×3 matrix A of the above equation reads: $\det(A) = 9(\Sigma_1 + \Sigma_2 + \Sigma_3) = 0$, since $\Sigma_1 + \Sigma_2 + \Sigma_3 = 0$. Thus, rank of $A < 3$. One may easily check that all minors (M_k , $k = 1, 2, 3$) of the 2×2 submatrixes of the matrix A are of the form $M_k = \pm 3(1 + \Sigma_k)$. Since we cannot have $1 + \Sigma_k = 0, \forall k$ due to $\Sigma_1 + \Sigma_2 + \Sigma_3 = 0$, the rank of the A matrix equals 2. Suppose we choose

$$B = \begin{bmatrix} \Sigma_1 - 2 & 1 + \Sigma_1 \\ 1 + \Sigma_2 & \Sigma_2 - 2 \end{bmatrix} \quad (\text{B12})$$

to play the role of a nonsingular submatrix of A . Since $\det B = 3(1 + \Sigma_3)$, the rank of B equals 2 if we have

$$1 + \Sigma_3 \neq 0. \quad (\text{B13})$$

Using Cramer's rules we find the following solution to (B11):

$$\pi_1 = \Pi(1 + \Sigma_1), \quad \pi_2 = \Pi(1 + \Sigma_2) \quad \pi_3 = \Pi(1 + \Sigma_3), \quad (\text{B14})$$

where we have redefined an arbitrary variable $\pi_3 = \Pi \in C^1(\mathbb{R})$ by taking $\pi_3 = \Pi(1 + \Sigma_3)$, which is allowed as $(1 + \Sigma_3) \neq 0$. It is clear that one can get the solution (B14) assuming that either $1 + \Sigma_1 \neq 0$ or $1 + \Sigma_2 \neq 0$, instead of (B13). Therefore, our solution (B14) is independent on the choice of the minor M_k connected with the matrix A of (B11). We conclude that the general solution to the matrix equation (B11) is defined by (B14).

Using (14) we obtain

$$N_\alpha = 3 \exp(2q_\alpha) / (\pi_1 + \pi_2 + \pi_3), \quad (\text{B15})$$

that leads to

$$\exp(2q_1) = N_1(\pi_1 + \pi_2 + \pi_3)/3, \quad \exp(q_2 - q_1) = \sqrt{N_2/N_1}, \quad \exp(q_3 - q_2) = \sqrt{N_3/N_2}. \quad (\text{B16})$$

Combining (B4) - (B6) we obtain

$$\exp(2q_1) = \dot{\pi}_1 + \dot{\pi}_2 + \dot{\pi}_3, \quad \exp(q_2 - q_1) = 2\dot{\pi}_1 + \dot{\pi}_2 + \dot{\pi}_3, \quad \exp(q_3 - q_2) = \dot{\pi}_1 + \dot{\pi}_2. \quad (\text{B17})$$

Comparing (B16) with (B17), and using the solution (B14), we get

$$\dot{\pi}_1 + \dot{\pi}_2 + \dot{\pi}_3 = \Pi N_1, \quad (\text{B18})$$

$$2\dot{\pi}_1 + \dot{\pi}_2 + \dot{\pi}_3 = \sqrt{N_2/N_1}, \quad (\text{B19})$$

$$\dot{\pi}_1 + \dot{\pi}_2 = \sqrt{N_3/N_2}, \quad (\text{B20})$$

Which can be presented in a matrix form as follows:

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} \dot{\pi}_1 \\ \dot{\pi}_2 \\ \dot{\pi}_3 \end{bmatrix} = \begin{bmatrix} \Pi N_1 \\ \sqrt{N_2/N_1} \\ \sqrt{N_3/N_2} \end{bmatrix}. \quad (\text{B21})$$

One may easily verify that determinant of the matrix defining (B21) equals one, so the system has only one solution. It is found to be:

$$\dot{\pi}_1 = \sqrt{N_2/N_1} - \tilde{\Pi}, \quad \dot{\pi}_2 = \sqrt{N_3/N_2} - \sqrt{N_2/N_1} + \tilde{\Pi}, \quad \dot{\pi}_3 = -\sqrt{N_3/N_2} + \tilde{\Pi}, \quad (\text{B22})$$

where $\tilde{\Pi} := \Pi N_1$.

An arbitrary variable Π that occurs in (B14) and (B22) can be fixed by the constraint (B8). It leads to the following equation for Π :

$$(3 + \Sigma_1 \Sigma_2 + \Sigma_1 \Sigma_3 + \Sigma_2 \Sigma_3) \Pi^2 - N_1 \Pi - (\sqrt{N_2/N_1} + \sqrt{N_3/N_2}) = 0, \quad (\text{B23})$$

where $\Sigma_1 + \Sigma_2 + \Sigma_3 = 0$.

Appendix C: The Poincaré type variables

Since examination of phase space at ‘infinite region’, (B9), is difficult mathematically, we change coordinates of the phase space to map the set of critical points (B9) onto a finite region. We map the infinite space \mathbb{R}^6 into a finite Poincaré sphere, parameterized by Cartesian coordinates $(X_1, X_2, X_3, P_1, P_2, P_3)$, as follows:

$$x_1 =: \frac{X_1}{1-r}, \quad (\text{C1})$$

$$x_2 =: \frac{X_2}{1-r}, \quad (\text{C2})$$

$$x_3 =: \frac{X_3}{1-r}, \quad (\text{C3})$$

$$p_1 =: \frac{P_1}{1-r}, \quad (\text{C4})$$

$$p_2 =: \frac{P_2}{1-r}, \quad (\text{C5})$$

$$p_3 =: \frac{P_3}{1-r}, \quad (\text{C6})$$

where $r^2 = X_1^2 + X_2^2 + X_3^2 + P_1^2 + P_2^2 + P_3^2$, and where we redefined the variables: $x_k := q_k, p_k := \pi_k$ ($k = 1, 2, 3$) to get the connection with the results of our previous

paper (see, Eq. (38) of [6]). We also rescale the time parameter τ by defining the new time parameter T such that $dT := d\tau/(1-r)$. In these coordinates our phase space is contained within a sphere of radius one – ‘infinities’ correspond to $r = 1$.

If the mapping is *canonical*, we should have:

$$\{X_l, X_k\}_{x,p} = 0 = \{P_l, P_k\}_{x,p}, \quad \{X_l, P_k\}_{x,p} = \delta_{lk}. \quad (\text{C7})$$

The map (C1)-(C6) is not canonical, because we have:

$$\{X_k, X_l\}_{x,p} = (1-r)g(a)(x_k p_l - x_l p_k), \quad (\text{C8})$$

$$\{P_k, P_l\}_{x,p} = (1-r)f(a)(x_k p_l - x_l p_k), \quad (\text{C9})$$

$$\{X_k, P_l\}_{x,p} = (1-r)^2 \delta_{kl} - (1-r)(f(a)x_k x_l + g(a)p_k p_l), \quad (\text{C10})$$

where $a := r^2/(1-r)^2$, $f(a) \neq 0$, $g(a) \neq 0$. It is clear that there is no chance to get (C7) for any r including the limit $r \rightarrow 1$.

The insertion of (C1)-(C6) into (B1)-(B6) gives:

$$\left(\frac{X_1}{1-r}\right)' = \frac{1}{2}(-P_1 + P_2 + P_3), \quad (\text{C11})$$

$$\left(\frac{X_2}{1-r}\right)' = \frac{1}{2}(P_1 - P_2 + P_3), \quad (\text{C12})$$

$$\left(\frac{X_3}{1-r}\right)' = \frac{1}{2}(P_1 + P_2 - P_3), \quad (\text{C13})$$

$$\left(\frac{P_1}{1-r}\right)' = (1-r)\left(2 \exp \frac{2X_1}{1-r} - \exp \frac{X_2 - X_1}{1-r}\right), \quad (\text{C14})$$

$$\left(\frac{P_2}{1-r}\right)' = (1-r)\left(\exp \frac{X_2 - X_1}{1-r} - \exp \frac{X_3 - X_2}{1-r}\right), \quad (\text{C15})$$

$$\left(\frac{P_3}{1-r}\right)' = (1-r)\left(\exp \frac{X_3 - X_2}{1-r}\right), \quad (\text{C16})$$

where prime denotes derivative with respect to the new time parameter T .

To find the fixed points we insert $X'_1 = 0 = X'_2 = X'_3 = P'_1 = P'_2 = P'_3$ into (C11)-(C16) by using the elementary formulas:

$$r' = \frac{d}{dT}r = (X_1 X'_1 + X_2 X'_2 + X_3 X'_3 + P_1 P'_1 + P_2 P'_2 + P_3 P'_3)/r \quad (\text{C17})$$

and, e.g.

$$\frac{d}{dT}\left(\frac{X_1}{1-r}\right) = \frac{X'_1(1-r) + X_1 r'}{(1-r)^2}. \quad (\text{C18})$$

After rearrangement of terms we finally get:

$$-P_1 + P_2 + P_3 = 0, \quad (\text{C19})$$

$$P_1 - P_2 + P_3 = 0, \quad (\text{C20})$$

$$P_1 + P_2 - P_3 = 0, \quad (\text{C21})$$

$$2 \exp \frac{2X_1}{1-r} - \exp \frac{X_2 - X_1}{1-r} = 0, \quad (\text{C22})$$

$$\exp \frac{X_2 - X_1}{1-r} - \exp \frac{X_3 - X_2}{1-r} = 0, \quad (\text{C23})$$

$$\exp \frac{X_3 - X_2}{1-r} = 0. \quad (\text{C24})$$

The solution to (C19)-(C21) reads: $P_1 = 0 = P_2 = P_3$. The equations (C22)-(C24) can be satisfied in the limit $r \mapsto 1$ if

$$\lim_{r \rightarrow 1^-} \exp \frac{2X_1}{1-r} = 0 = \lim_{r \rightarrow 1^-} \exp \frac{X_2 - X_1}{1-r} = \lim_{r \rightarrow 1^-} \exp \frac{X_3 - X_2}{1-r}, \quad (\text{C25})$$

which leads to the condition: $X_3 < X_2 < X_1 < 0$. Therefore, the critical subspace is defined to be:

$$S_P := \{(X_1, X_2, X_3, P_1, P_2, P_3) \mid (X_3 < X_2 < X_1 < 0) \wedge (P_1 = 0 = P_2 = P_3)\}. \quad (\text{C26})$$

It is not difficult to verify that the transformation (C1)-(C6) does not map S_B into S_P .

It is clear that any point of S_P , in the limit $r \rightarrow 1^-$, satisfies the constraint (B7) which in the variables (C1)-(C6) has the form:

$$\frac{1}{2(1-r)^2}(P_1P_2 + P_1P_3 + P_2P_3) - \frac{1}{4(1-r)^2}(P_1^2 + P_2^2 + P_3^2) \quad (\text{C27})$$

$$- \exp \frac{2X_1}{1-r} - \exp \frac{X_2 - X_1}{1-r} - \exp \frac{X_3 - X_2}{1-r} = 0. \quad (\text{C28})$$

One can resolve (either manually or by symbolic computations) the nonlinear vector field (C11)-(C16) with respect to the derivatives X'_1, X'_2, \dots, P'_3 , and find the corresponding Jacobian. Its value at any point of the subspace S_P (in the limit $r \mapsto 1$) turns out to be a six dimensional zero matrix. It means that linearization of the exact vector field, at the set of critical points S_P , cannot help in the understanding of the mathematical structure of the space of orbits of considered vector field. An

examination of the nonlinearity cannot be avoided. One may say, formally, that the set S_P consists of the *nonhyperbolic* type of fixed points.

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